



Math 2940 Worksheet  
Complex Eigenvalues, Dynamical Systems

Week 12  
November 14th, 2019

This worksheet covers material from **Sections 5.5 - 5.7**. Please work in collaboration with your classmates to complete the following exercises - this means sharing ideas and asking each other questions.

**Question 1.** Show that if  $a$  and  $b$  are real, then the eigenvalues of  $A = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$  are  $a \pm bi$ , with corresponding eigenvectors  $\begin{bmatrix} 1 \\ -i \end{bmatrix}$  and  $\begin{bmatrix} 1 \\ i \end{bmatrix}$ .

**Question 2.** The matrix  $A$  below has eigenvalues  $1$ ,  $\frac{2}{3}$ , and  $\frac{1}{3}$ , with corresponding eigenvectors  $\mathbf{v}_1$ ,  $\mathbf{v}_2$ , and  $\mathbf{v}_3$ :

$$A = \frac{1}{9} \begin{bmatrix} 7 & -2 & 0 \\ -2 & 6 & 2 \\ 0 & 2 & 5 \end{bmatrix}, \quad \mathbf{v}_1 = \begin{bmatrix} -2 \\ 2 \\ 1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix}$$

(a) Find the solution of the equation  $\mathbf{x}_{k+1} = A\mathbf{x}_k$  if  $\mathbf{x}_0 = \begin{bmatrix} 1 \\ 11 \\ -2 \end{bmatrix}$ .

(b) What happens to the sequence  $\{\mathbf{x}_k\}$  from part (a) as  $k \rightarrow \infty$ ?

(c) Would your answer to part (b) be the same for all values of  $\mathbf{x}_0$ ? Why or why not?

**Question 3.** Here we are interested in how the populations of two species change over time. Let  $x(t)$  represent the population of prey, and  $y(t)$  represent the population of predators.

Suppose that the change in populations over time can be described by the following linear system of differential equations:

$$\begin{aligned}x' &= 7x - y \\y' &= 3x + 3y\end{aligned}$$

Given the initial conditions  $\begin{bmatrix} x(0) \\ y(0) \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$ , find the solution to this system of differential equations.

**Question 4.** Let  $A = \begin{bmatrix} -3 & 2 \\ -1 & -1 \end{bmatrix}$ .

(a) Construct the general solution of  $\mathbf{x}' = A\mathbf{x}$  involving complex eigenfunctions

(b) Using your answer to part (a), obtain the general real solution

**Question 5.**

- (a) Not every matrix is diagonalizable. Consider the matrix  $A = \begin{bmatrix} 3 & -1 \\ 1 & 1 \end{bmatrix}$ . Compute the eigenvalues of  $A$  and compute the corresponding eigenvector. How many distinct eigenvalues and eigenvectors does  $A$  have?

- (b) On the other hand, consider the matrix  $B = \begin{bmatrix} 2 & -1 & 1 \\ 0 & 2 & 0 \\ 0 & -1 & 3 \end{bmatrix}$ . How many distinct eigenvalues and eigenvectors does  $B$  have?

(c) Write down the fundamental solution to the initial value problem

$$\mathbf{x}' = A\mathbf{x}, \quad \mathbf{x}(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

where  $A = \begin{bmatrix} 3 & -1 \\ 1 & 1 \end{bmatrix}$  is the matrix from part (a).

**Answer to Question 1.** To find the eigenvalues, we calculate the roots of the characteristic equation:

$$\begin{aligned}\det(A - \lambda I) &= \det \left( \begin{bmatrix} a - \lambda & -b \\ b & a - \lambda \end{bmatrix} \right) = 0 \\ (a - \lambda)^2 + b^2 &= 0 \\ \lambda^2 - 2a\lambda + a^2 + b^2 &= 0\end{aligned}$$

Using the quadratic formula,

$$\lambda = \frac{2a \pm \sqrt{4a^2 - 4(a^2 + b^2)}}{2} = \frac{2a \pm \sqrt{-4b^2}}{2}$$

So the eigenvalues are:

$$\boxed{\lambda = a \pm bi}$$

Now, to find the eigenvalue associated with  $\lambda_1 = a + bi$ , we compute the nullspace of  $A - \lambda_1 I$

$$A - (a + bi)I = \begin{bmatrix} a - (a + bi) & -b \\ b & a - (a + bi) \end{bmatrix} = \begin{bmatrix} -bi & -b \\ b & -bi \end{bmatrix}$$

Row reducing,

$$\begin{bmatrix} -bi & -b \\ b & -bi \end{bmatrix} \xrightarrow{i \cdot R1} \begin{bmatrix} b & -bi \\ b & -bi \end{bmatrix} \xrightarrow{R2 - R1} \begin{bmatrix} b & -bi \\ 0 & 0 \end{bmatrix}$$

So the nullspace is described by the equation  $bx_1 - bix_2 = 0$ . Choosing  $x_1 = 1$ , it follows that  $x_2 = -i$ .

$$\boxed{\text{Therefore } \begin{bmatrix} 1 \\ -i \end{bmatrix} \text{ is an eigenvector with eigenvalue } a + bi}$$

Similarly for the other eigenvalue, we compute the nullspace of  $A - \lambda_2 I$  as

$$A - (a - bi)I = \begin{bmatrix} a - (a - bi) & -b \\ b & a - (a - bi) \end{bmatrix} = \begin{bmatrix} bi & -b \\ b & bi \end{bmatrix}$$

Row reducing,

$$\begin{bmatrix} bi & -b \\ b & bi \end{bmatrix} \xrightarrow{i \cdot R1} \begin{bmatrix} -b & -bi \\ b & bi \end{bmatrix} \xrightarrow{R2 + R1} \begin{bmatrix} -b & -bi \\ 0 & 0 \end{bmatrix}$$

So the nullspace is described by the equation  $-bx_1 - bix_2 = 0$ . Choosing  $x_1 = 1$ , it follows that  $x_2 = i$ .

$$\boxed{\text{Therefore } \begin{bmatrix} 1 \\ i \end{bmatrix} \text{ is an eigenvector with eigenvalue } a - bi}$$

## Answer to Question 2.

- (a) First we want to write the initial conditions  $\mathbf{x}_0$  in terms of the eigenvectors, i.e. find constants  $c$  such that

$$\begin{aligned}\mathbf{x}_0 &= c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + c_3 \mathbf{v}_3 \\ \begin{bmatrix} 1 \\ 11 \\ -2 \end{bmatrix} &= c_1 \begin{bmatrix} -2 \\ 2 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix} + c_3 \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix}\end{aligned}$$

This is equivalent to the augmented matrix:

$$\left[ \begin{array}{ccc|c} -2 & 2 & 1 & 1 \\ 2 & 1 & 2 & 11 \\ 1 & 2 & -2 & -2 \end{array} \right]$$

Row reducing,

$$\begin{aligned} & \left[ \begin{array}{ccc|c} -2 & 2 & 1 & 1 \\ 2 & 1 & 2 & 11 \\ 1 & 2 & -2 & -2 \end{array} \right] \xrightarrow{R2+R1} \left[ \begin{array}{ccc|c} -2 & 2 & 1 & 1 \\ 0 & 3 & 3 & 12 \\ 1 & 2 & -2 & -2 \end{array} \right] \xrightarrow{R3+\frac{1}{2}R1} \left[ \begin{array}{ccc|c} -2 & 2 & 1 & 1 \\ 0 & 3 & 3 & 12 \\ 0 & 3 & -3/2 & -3/2 \end{array} \right] \\ & \xrightarrow{R3-R2} \left[ \begin{array}{ccc|c} -2 & 2 & 1 & 1 \\ 0 & 3 & 3 & 12 \\ 0 & 0 & -9/2 & -27/2 \end{array} \right] \xrightarrow{\frac{-2}{9}R3} \left[ \begin{array}{ccc|c} -2 & 2 & 1 & 1 \\ 0 & 3 & 3 & 12 \\ 0 & 0 & 1 & 3 \end{array} \right] \xrightarrow{\frac{1}{3}R2} \left[ \begin{array}{ccc|c} -2 & 2 & 1 & 1 \\ 0 & 1 & 1 & 4 \\ 0 & 0 & 1 & 3 \end{array} \right] \\ & \xrightarrow{R2-R3} \left[ \begin{array}{ccc|c} -2 & 2 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 3 \end{array} \right] \xrightarrow{R1-R3} \left[ \begin{array}{ccc|c} -2 & 2 & 0 & -2 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 3 \end{array} \right] \xrightarrow{\frac{-1}{2}R1} \left[ \begin{array}{ccc|c} 1 & -1 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 3 \end{array} \right] \\ & \xrightarrow{R1+R2} \left[ \begin{array}{ccc|c} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 3 \end{array} \right] \end{aligned}$$

Therefore the initial condition can be written in terms of the eigenvectors as:

$$\mathbf{x}_0 = 2 \begin{bmatrix} -2 \\ 2 \\ 1 \end{bmatrix} + 1 \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix} + 3 \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix}$$

Using the eigenvalues and eigenvectors, we can compute

$$\boxed{\mathbf{x}_k = A^k \mathbf{x}_0 = 2(1)^k \begin{bmatrix} -2 \\ 2 \\ 1 \end{bmatrix} + \left(\frac{2}{3}\right)^k \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix} + 3 \left(\frac{1}{3}\right)^k \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix}}$$

*Note:* This is equivalent to computing the diagonalization  $A = PDP^{-1}$ , and then finding the solution as  $\mathbf{x}_k = PD^k P^{-1} \mathbf{x}_0$ .

- Computing  $P^{-1} \mathbf{x}_0$  is equivalent to finding the coefficients  $c_1$ ,  $c_2$ , and  $c_3$ .
- Multiplying by  $D^k$  contributes the eigenvalue to the  $k$ -th power terms above
- Multiplying by  $P$  contributes the eigenvectors in the above solution.



(b) As  $k \rightarrow \infty$ , we see that both the  $(\frac{2}{3})^k$  and  $(\frac{1}{3})^k$  terms will go to zero, leaving

$$\lim_{k \rightarrow \infty} \mathbf{x}_k = 2 \begin{bmatrix} -2 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} -4 \\ 4 \\ 2 \end{bmatrix}$$

(c) If we write the initial conditions as  $\mathbf{x}_0 = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + c_3 \mathbf{v}_3$ , then we can see from the previous problems that

$$\lim_{k \rightarrow \infty} \mathbf{x}_k = c_1 \begin{bmatrix} -2 \\ 2 \\ 1 \end{bmatrix}$$

Since  $c_1$  clearly does depend upon the value of  $\mathbf{x}_0$ , then

No, our answer would not be the same for all values of  $\mathbf{x}_0$ .

**Answer to Question 3.** First, we can write this linear system of differential equations in matrix form as

$$\begin{bmatrix} x \\ y \end{bmatrix}' = \begin{bmatrix} 7 & -1 \\ 3 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

Now we want to compute the eigenvalues and eigenvectors of  $A = \begin{bmatrix} 7 & -1 \\ 3 & 3 \end{bmatrix}$ . Finding the roots of the characteristic equation,

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det \left( \begin{bmatrix} 7 - \lambda & -1 \\ 3 & 3 - \lambda \end{bmatrix} \right) &= 0 \\ (7 - \lambda)(3 - \lambda) + 3 &= 0 \\ \lambda^2 - 10\lambda + 24 &= 0 \\ (\lambda - 4)(\lambda - 6) &= 0 \end{aligned}$$

So we can see that the two eigenvalues are  $\lambda = 4$  and  $\lambda = 6$ .

To find the eigenvector corresponding to  $\lambda = 4$ , we find the nullspace of  $A - 4I$  by row reducing:

$$A - 4I = \begin{bmatrix} 3 & -1 \\ 3 & -1 \end{bmatrix} \xrightarrow{\text{R2} - \text{R1}} \begin{bmatrix} 3 & -1 \\ 0 & 0 \end{bmatrix}$$

Plugging  $x_1 = 1$  into  $3x_1 - x_2 = 0$ , we get that  $x_2 = 3$ , and therefore

$$\begin{bmatrix} 1 \\ 3 \end{bmatrix} \text{ is an eigenvector of } A \text{ with eigenvalue } \lambda = 4$$

Similarly, we find the eigenvector corresponding to  $\lambda = 6$ ,

$$A - 6I = \begin{bmatrix} 1 & -1 \\ 3 & -3 \end{bmatrix} \xrightarrow{\text{R2} - 3\text{R1}} \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix}$$

Plugging  $x_1 = 1$  into  $x_1 - x_2 = 0$ , we get that  $x_2 = 1$ , and therefore

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} \text{ is an eigenvector of } A \text{ with eigenvalue } \lambda = 6$$

We can put these together to get that the general solution is:

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ 3 \end{bmatrix} e^{4t} + c_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{6t}$$

for some constants  $c_1$  and  $c_2$ .

Plugging in the initial conditions at  $t = 0$ , we get that

$$\begin{aligned} x(0) &= c_1 + c_2 = 3 \\ y(0) &= 3c_1 + c_2 = 2 \end{aligned}$$

Putting this in augmented matrix form and row reducing,

$$\left[ \begin{array}{cc|c} 1 & 1 & 3 \\ 3 & 1 & 2 \end{array} \right] \xrightarrow{R_2 - R_1} \left[ \begin{array}{cc|c} 1 & 1 & 3 \\ 2 & 0 & -1 \end{array} \right] \xrightarrow{\frac{1}{2} \cdot R_2} \left[ \begin{array}{cc|c} 1 & 1 & 3 \\ 1 & 0 & -\frac{1}{2} \end{array} \right] \xrightarrow{R_1 - R_2} \left[ \begin{array}{cc|c} 0 & 1 & \frac{7}{2} \\ 1 & 0 & -\frac{1}{2} \end{array} \right]$$

From this we can see that  $c_1 = -\frac{1}{2}$  and  $c_2 = \frac{7}{2}$ , so the solution to this initial value problem is

$$\boxed{\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = -\frac{1}{2} \begin{bmatrix} 1 \\ 3 \end{bmatrix} e^{4t} + \frac{7}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{6t}}$$

#### Answer to Question 4.

(a) First, we find the eigenvalues of  $A$  by finding the roots of the characteristic equation:

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det \left( \begin{bmatrix} -3 - \lambda & 2 \\ -1 & -1 - \lambda \end{bmatrix} \right) &= 0 \\ (-3 - \lambda)(-1 - \lambda) + 2 &= 0 \\ \lambda^2 + 4\lambda + 5 &= 0 \end{aligned}$$

Using the quadratic formula, the eigenvalues are

$$\lambda = \frac{-4 \pm \sqrt{16 - 20}}{2} = \frac{-4 \pm \sqrt{-4}}{2} = -2 \pm i$$

First we find the eigenvector associated to  $\lambda = -2 + i$

$$A - (-2 + i)I = \begin{bmatrix} -1 - i & 2 \\ -1 & 1 - i \end{bmatrix} \xrightarrow{(-1-i) \cdot R_1} \begin{bmatrix} 2 & -2 + 2i \\ -1 & 1 - i \end{bmatrix} \xrightarrow{R_2 + \frac{1}{2} \cdot R_1} \begin{bmatrix} 2 & -2 + 2i \\ 0 & 0 \end{bmatrix}$$

Plugging  $x_2 = 1$  into  $2x_1 + (-2 + 2i)x_2 = 0$ , we get that  $x_1 = 1 - i$ , and therefore

$$\begin{bmatrix} 1 - i \\ 1 \end{bmatrix} \text{ is an eigenvector of } A \text{ with eigenvalue } \lambda = -2 + i$$

Now to find the eigenvector associated to  $\lambda = -2 - i$

$$A - (-2 - i)I = \begin{bmatrix} -1 + i & 2 \\ -1 & 1 + i \end{bmatrix} \xrightarrow{(-1+i) \cdot R_1} \begin{bmatrix} 2 & -2 - 2i \\ -1 & 1 + i \end{bmatrix} \xrightarrow{R_2 + \frac{1}{2} \cdot R_1} \begin{bmatrix} 2 & -2 - 2i \\ 0 & 0 \end{bmatrix}$$

Plugging  $x_2 = 1$  into  $2x_1 + (-2 - 2i)x_2 = 0$ , we get that  $x_1 = 1 + i$ , and therefore

$$\begin{bmatrix} 1 + i \\ 1 \end{bmatrix} \text{ is an eigenvector of } A \text{ with eigenvalue } \lambda = -2 - i$$

Putting these together, the general solution using complex eigenfunctions is:

$$\boxed{\mathbf{x}(t) = c_1 \begin{bmatrix} 1 - i \\ 1 \end{bmatrix} e^{(-2+i)t} + c_2 \begin{bmatrix} 1 + i \\ 1 \end{bmatrix} e^{(-2-i)t}}$$

(b) To obtain the general real solution, we want to split up the first fundamental solution into real and imaginary parts:

$$\begin{bmatrix} 1 - i \\ 1 \end{bmatrix} e^{(-2+i)t} = \operatorname{Re}(t) + i \cdot \operatorname{Im}(t)$$

Expanding the left hand side using Euler's formula  $e^{i\theta} = \cos(\theta) + i \sin(\theta)$ ,

$$\begin{aligned} &= \begin{bmatrix} 1 - i \\ 1 \end{bmatrix} e^{-2t} \cos(t) + i \begin{bmatrix} 1 - i \\ 1 \end{bmatrix} e^{-2t} \sin(t) \\ &= \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{-2t} \cos(t) + i \begin{bmatrix} -1 \\ 0 \end{bmatrix} e^{-2t} \cos(t) + i \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{-2t} \sin(t) + \begin{bmatrix} 1 \\ 0 \end{bmatrix} e^{-2t} \sin(t) \end{aligned}$$

Rearranging,

$$= \begin{bmatrix} \cos(t) + \sin(t) \\ \cos(t) \end{bmatrix} e^{-2t} + i \begin{bmatrix} \sin(t) - \cos(t) \\ \sin(t) \end{bmatrix} e^{-2t}$$

Therefore the real and imaginary parts are:

$$\operatorname{Re}(t) = \begin{bmatrix} \cos(t) + \sin(t) \\ \cos(t) \end{bmatrix} e^{-2t}, \quad \text{and} \quad \operatorname{Im}(t) = \begin{bmatrix} \sin(t) - \cos(t) \\ \sin(t) \end{bmatrix} e^{-2t}$$

And we can use these to construct the general real solution:

$$\boxed{\mathbf{x}(t) = c_1 \begin{bmatrix} \cos(t) + \sin(t) \\ \cos(t) \end{bmatrix} e^{-2t} + c_2 \begin{bmatrix} \sin(t) - \cos(t) \\ \sin(t) \end{bmatrix} e^{-2t}}$$

### Answer to Question 5.

- (a) First we compute the eigenvalues and eigenvectors of  $A = \begin{bmatrix} 3 & -1 \\ 1 & 1 \end{bmatrix}$ .

Finding the roots of the characteristic equation,

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det \left( \begin{bmatrix} 3 - \lambda & -1 \\ 1 & 1 - \lambda \end{bmatrix} \right) &= 0 \\ (3 - \lambda)(1 - \lambda) + 1 &= 0 \\ \lambda^2 - 4\lambda + 4 &= 0 \\ (\lambda - 2)^2 &= 0 \end{aligned}$$

So  $A$  only has the single distinct eigenvalue of  $\lambda = 2$ .

Finding the corresponding eigenvector(s),

$$A - 2I = \begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix} \xrightarrow{R2 - R1} \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix}$$

So the nullspace is described by  $x_1 - x_2 = 0$ . One possible non-zero solution is  $x_1 = x_2 = 1$ , so therefore

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} \text{ is the only eigenvector of } A.$$

- (b) Now to compute the eigenvalues and eigenvectors of  $B = \begin{bmatrix} 2 & -1 & 1 \\ 0 & 2 & 0 \\ 0 & -1 & 3 \end{bmatrix}$ ,

Finding the characteristic equation using a co-factor expansion in the first column,

$$\det(B - \lambda I) = \det \left( \begin{bmatrix} 2 - \lambda & -1 & 1 \\ 0 & 2 - \lambda & 0 \\ 0 & -1 & 3 - \lambda \end{bmatrix} \right) = (2 - \lambda) \det \left( \begin{bmatrix} 2 - \lambda & 0 \\ -1 & 3 - \lambda \end{bmatrix} \right) = (2 - \lambda)^2(3 - \lambda) = 0$$

So there are two distinct eigenvalues:  $\lambda = 2$  and  $\lambda = 3$ .

First, we find any eigenvectors associated to  $\lambda = 2$ ,

$$B - 2I = \begin{bmatrix} 0 & -1 & 1 \\ 0 & 0 & 0 \\ 0 & -1 & 1 \end{bmatrix} \xrightarrow{R3 - R1} \begin{bmatrix} 0 & -1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

So the nullspace is described by the equation  $-x_2 + x_3 = 0$ .

Because  $x_1$  is a free variable, we get a solution of  $x_1 = 1$ ,  $x_2 = 0$ , and  $x_3 = 0$ .

Setting  $x_1 = 0$  and plugging  $x_3 = 1$  into  $-x_2 + x_3 = 0$ , we get that  $x_2 = 1$ . Therefore,

$$\text{Both } \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \text{ and } \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \text{ are eigenvectors of } B \text{ with eigenvalue } \lambda = 2$$

Now, we find any eigenvectors associated to  $\lambda = 3$ ,

$$B - 3I = \begin{bmatrix} -1 & -1 & 1 \\ 0 & -1 & 0 \\ 0 & -1 & 0 \end{bmatrix} \xrightarrow{R3 - R2} \begin{bmatrix} -1 & -1 & 1 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R1 - R2} \begin{bmatrix} -1 & 0 & 1 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Setting the free variable  $x_3 = 1$ , we get that  $x_1 = 1$  and  $x_2 = 0$ , so

$\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$  is an eigenvector of  $B$  with eigenvalue  $\lambda = 3$

All together, there are three eigenvectors but only two distinct eigenvalues.

- (c) Because  $A$  only has one eigenvector (see part (a)), we will be unable to fully diagonalize  $A$ . Thus we will be unable to fully de-couple the equations for  $x_1(t)$  and  $x_2(t)$ .

However, with the right change-of-coordinates, we can still “triangularize” the matrix  $A$ . This will allow us to solve for  $x_1(t)$ , and then use our solution for  $x_2(t)$  to solve for  $x_1(t)$ .

First, we will define a change-of-coordinates matrix  $P = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ .

(The exact change-of-coordinates is not important, only that one of our columns correspond to the eigenvector we found in part (a).)

We can then easily calculate that  $P^{-1} = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$

Defining a new set of variables as  $P\mathbf{y}(t) = \mathbf{x}(t)$ , we see that they satisfy the system of equations

$$P\mathbf{y}'(t) = AP\mathbf{y}(t)$$

Multiplying both sides on the left by  $P^{-1}$ ,

$$\mathbf{y}'(t) = P^{-1}AP\mathbf{y}(t)$$

Using matrix multiplication, we can compute

$$P^{-1}AP = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 3 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 3 & 2 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 1 & 2 \end{bmatrix}$$

Therefore our system of equations is

$$\begin{bmatrix} y_1'(t) \\ y_2'(t) \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

The first equation is simply  $y_1' = 2y_1$ , which has a solution of

$$y_1(t) = c_1 e^{2t}$$

Plugging that into the second equation, we get

$$y_2' = c_1 e^{2t} + 2y_2$$

This is a first-order linear ODE, so we can solve it using integrating factors. Rearranging,

$$y_2' - 2y_2 = c_1 e^{2t}$$

Multiplying both sides by  $e^{-2t}$ ,

$$e^{-2t}y_2' - 2e^{-2t}y_2 = c_1$$

Using the product rule (in reverse) on the left hand side,

$$\frac{d}{dt}(e^{-2t}y_2) = c_1$$

Integrating both sides,

$$e^{-2t}y_2 = c_1 t + c_2$$

Multiplying both sides by  $e^{2t}$ ,

$$y_2 = c_1 t e^{2t} + c_2 e^{2t}$$

And therefore our general solution is

$$\begin{bmatrix} y_1(t) \\ y_2(t) \end{bmatrix} = \begin{bmatrix} c_1 e^{2t} \\ c_1 t e^{2t} + c_2 e^{2t} \end{bmatrix}$$

Undoing our change-of-coordinates,

$$\mathbf{x} = P\mathbf{y} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} c_1 e^{2t} \\ c_1 t e^{2t} + c_2 e^{2t} \end{bmatrix} = \begin{bmatrix} c_1 t e^{2t} + (c_1 + c_2) e^{2t} \\ c_1 t e^{2t} + c_2 e^{2t} \end{bmatrix}$$

Plugging in the initial conditions  $\mathbf{x}(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ ,

$$\mathbf{x}(0) = \begin{bmatrix} c_1(0)e^0 + (c_1 + c_2)e^0 \\ c_1(0)e^0 + c_2e^0 \end{bmatrix} = \begin{bmatrix} c_1 + c_2 \\ c_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

So clearly  $c_1 = 1$  and  $c_2 = 0$ . Therefore the solution is

$$\mathbf{x} = \begin{bmatrix} t e^{2t} + e^{2t} \\ t e^{2t} \end{bmatrix}$$